Dual setting type, High accuracy temperature controller

■ Features

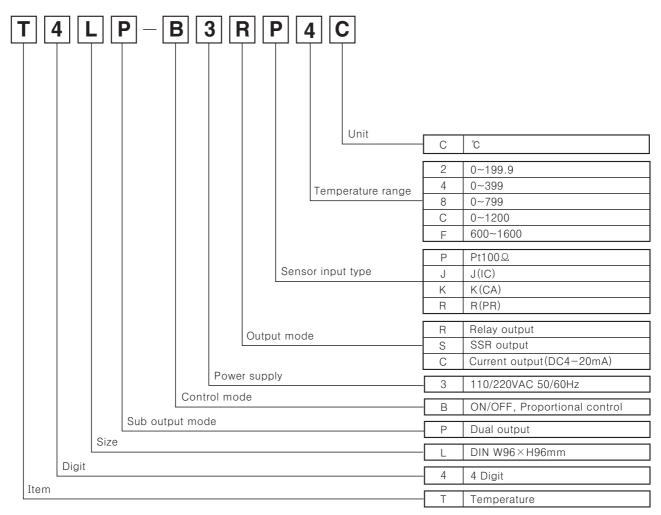
- •Dual setting type
- •High accuracy measuring function: ±0.5%
- Control heater and cooler at once
- •Use dual setting type of temperature when executing low temperature or precision control. In dual setting control type, the single output is operated as reverse, it is used for heater control. The dual output is used to control the operation of cooler normally.

The dual output is also used for an alarm.



Please read "Caution for your safety" in operation manual before using.

Ordering information



★See C-34 about sensor temperature range for selection.

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Dual Setting Type

■Temperature range for each sensor

Model		T4LP				
Sensor input		Thermocouples				RTD
type		J(IC)	K(CA)		R(PR)	Pt100Ω
$^{\circ}$	1600 1200 1000 800 400 200 100			1200℃	1600℃	
			799℃			
Standard scale		399℃	399℃		600°C	7°998 □ 7°9,991
range						
	0 -100	-				•

₩In case, the sensor is R(PR) type, it is not available to indicate the temperature and control correctly.

Specifations

Model		T4LP
Power supply		110/220VAC 50/60Hz
Allowable voltage range		90 ~ 110% of rated voltage
Power consumption		3VA
Display method		7 Segment LED Display
Character size		W9.5×H14.2mm
Display accuracy		F · S \pm 0.5% rdg ± 1 digit
Setting type		Digital switch setting
Setting ac	ccuracy	$F \cdot S \pm 0.5\%$
Sensor input		Thermocouples: K(CA), J(IC), R(PR) / RTD: Pt100Ω
Input line resistance		Thermocouples : Max. 100Ω , RTD : Max. 5Ω per a wire
	ON/OFF	Hysteresis F · S 0.2 ~ 3%
Control	Proportional	Proportional band : F · S 1 ~ 10%, Period : 20sec. fixed
RESET adjuster range		$F \cdot S \pm 3\%$ (Only for control deviation)
Control output		 Relay output: 1st out: 250VAC 3A 1c, 2nd out: 250VAC 2A 1c SSR output: 24VDC ±3V 20mA max. Current output: DC4-20mA Load 600Ω max.
Self-diag	ınosis	Includes burn out function
Insulation	resistance	Min. 100MΩ (at 500VDC mega)
Dielectric strength		2000VAC 50/60Hz for 1 minute
Noise stre	ength	$\pm 2 \mathrm{kV}$ the square wave noise(pulse width:1 μ s) by the noise simulator
Vibration	Mechanical	0.75mm amplitude at frequency of 10 ~ 55Hz in each of X, Y, Z directions for 1 hour
VIDIALIOII	Malfunction	0.5mm amplitude at frequency of 10 ~ 55Hz in each of X, Y, Z directions for 10 minutes
Shock	Mechanical	300m/s² (Approx. 30G) 3 times at X, Y, Z direction
Shock	Malfunction	100m/s² (Approx. 10G) 3 times at X, Y, Z direction
Relay	Mechanical	Min. 10,000,000 times
life cycle	Electrical	Min. 100,000 times (250VAC 3A at resistive load)
Ambient temperature		-10 ~ +50℃ (at non-freezing status)
Storage temperature		-20 ~ +60℃ (at non-freezing status)
Ambient humidity		35 ~ 85%RH
Unit weight		Approx. 487g

***(Note)** F.S is same with sensor measuring temperature range.

Ex) In case of using temperature is from $-99.9 \sim 199.9 \, ^{\circ}$ C, Full scale is 299.8.

(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/ Speed/ Pulse meter

(G) Display unit

(H) Sensor controller

(I) Switching power supply

(J) Proximity sensor

(K) Photo electric sensor

(L) Pressure sensor

(M) Rotary encoder

(N) Stepping motor & Driver & Controller

(O) Graphic panel

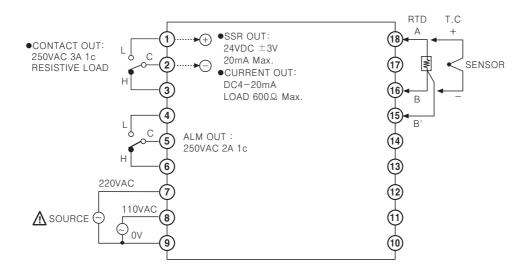
(P) Production stoppage models & replacement

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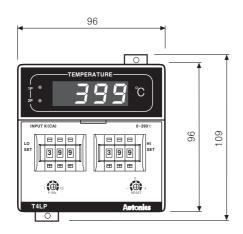
■Connections

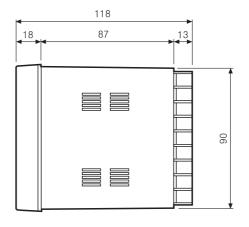
※RTD(Resistance Temperature Detector): Pt 100 Ω (3-wire type)

※Thermocouple: K, J, R

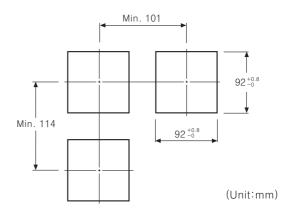


Dimensions





●Panel cut-out



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Dual Setting Type

■Proper usage

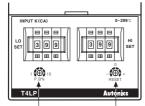
Operation

This controller has two outputs operated separately. In other words, it is able to set the values separately. Front Low Set runs with reverse operation as other common controllers and High Set runs by normal operation. It is able to control heater and cooler.



**Terminal block ①, ②, ③ are for Low set output and terminal block ④, ⑤, ⑥ are for High set output.

OUsing front adjuster



P.B adjuster

RESET adjuster

●P.B adjuster

In case of ON/OFF control, set variable F \cdot S 0.2~3% of hysteresis, and in case of proportional control, set variable F \cdot S 1~10% of hysteresis.

●RESET adjuster

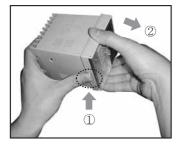
It corrects offset can be occurred by proportional control and has $F \cdot S \pm 3\%$ of adjustable range. Do not operate the adjuster when -3%



it is used as ON/OFF control.

- ①Turn left when offset value is higher than set value. (Direction ①)
- ②Turn right when offset value is lower than set value. (Direction ②)

Case detachment



OHow to select ON/OFF or proportional by plug pin

Factory specification is proportional control.

When using ON/OFF control, transfer the switch of control mode from P to F after detaching the case from its body.



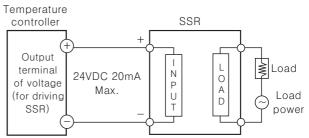
○Normal/Reverse operation

Reverse operation executes to output ON when process value is lower than setting value, and it is used for heating.

Normal operation is executed conversely and used for cooling. (This item runs as a reverse operation.)

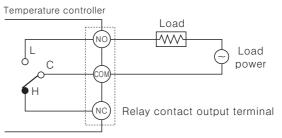
Application of temperature controller and load connection

SSR output



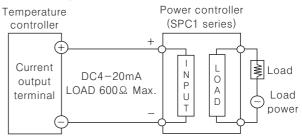
*When using voltage (for driving SSR) in the other purposes, do not exceed the range of the rated current.

Relay output



Output	Relay contact capacity		
1st OUT	250VAC 2A		
2nd OUT	250VAC 3A		

Current output



*The current value of DC4-20mA is available at lower than 600Ω of resistive load.

(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/ Speed/ Pulse meter

(G) Display unit

(H) Sensor controller

(I) Switching power supply

(J) Proximity sensor

(K) Photo electric sensor

(L) Pressure

(M) Rotary encoder

(N) Stepping motor & Driver & Controller

(O) Graphic panel

(P) Production stoppage models & replacement

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