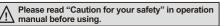
# Digital switch setting type

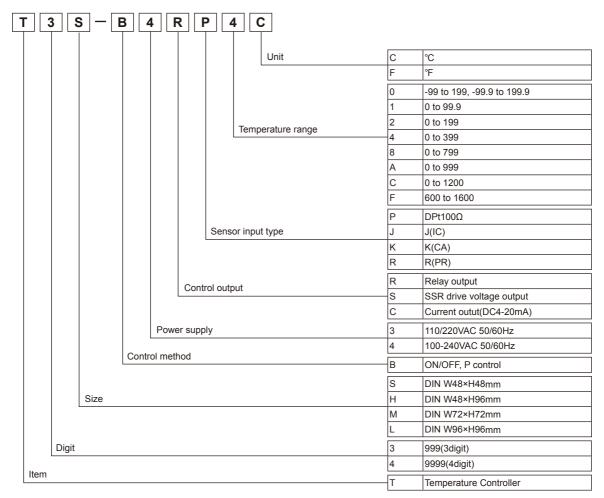
## Features

- Various size by DIN specification (W48×H48, W48×H96, W72×H72, W96×H96mm)
- Accuracy: F.S. ±0.5%(Except T3S)
- Free power: T3S Series





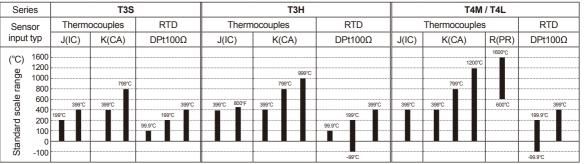
# Ordering information



 $<sup>\</sup>times$ Refer to the H-89 about sensor temperature range for selection.

H-88 Autonics

# **■** Temperature range for each sensor



XIn case input sensor is R(PR) type, it is not available to perform correct control under 600°C.

# Specifications

Series		T3S	ТЗН	T4M	T4L	
Power supply		100-240VAC 50/60Hz	110/220VAC 50/60Hz			
Allowable voltage range		90 to 110% of power supply				
Power consumption		Max. 5VA	Max. 3VA			
Display method		7 Segment(red) LED method				
Character size(W×H)		4.0×8.0mm	6.0×10.0mm	7.2×9.8mm	9.5×14.2mm	
Display accuracy		F.S. ±1% rdg ±1digit	g ±1digit F.S. ±0.5% rdg ±1digit			
Setting type		Digital setting				
Setting accuracy		F.S. ±1%	F.S. ±0.5%			
Sensor input		Thermocouples: K(CA), J(IC), R(PR) / RTD: DPt100 $\Omega$ $\times$ There is no R(PR) in T3S, T3H Series.				
Input line resistance		Thermocouples: Max. 100 $\Omega$ / RTD: Allowable line resistance max. 5 $\Omega$ per a wire				
Control method	ON/OFF control	Hysteresis: F.S. 0.5% ±0.2% fixed	Hysteresis: F.S. 0.2 to 3% variable			
	P control	Proportional band: F.S. ±3% fixed Period: 20sec. fixed	Proportional band: F.S. 1 to 10% variable, Period: 20sec. fixed			
RESET adjuster range		F.S. ±3% variable(revision of control deviation)				
Control output		Relay output: 250VAC 2A 1c SSR drive voltage output: 12VDC ±3V 20mA Max. Current output: DC4-20mA (load 600Ω Max.)	Relay output: 250VAC 3A 1c SSR output: 24VDC ±3V 20mA Max. Current output: DC4-20mA (load 600Ω Max.)			
Self-diagnosis		Built-in burn out function (cut off output when sensor is disconnected)				
Insulation resistance		Min. 100M $\Omega$ (at 500VDC megger)				
Dielectric strength		2,000VAC 50/60Hz for 1 min.				
Noise resistance		±1kV the square wave noise(pulse width: 1μs) by the noise simulator				
Vibration	Mechanical	0.75mm amplitude at frequency of 10 to 55Hz(for 1 min.) in each of X, Y, Z directions for 1 hour				
	Malfunction	0.5mm amplitude at frequency of 10 to 55Hz(for 1 min.) in each of X, Y, Z directions for 10 min.				
Shock	Mechanical	300m/s²(approx. 30G) in each of X, Y, Z directions for 3 times				
	Malfunction	100m/s²(approx. 10G) in each of X, Y, Z directions for 3 times				
Relay life cycle	Mechanical	Min. 10,000,000 operations				
	Electrical	Min. 100,000 operations(250VAC 3A at resistive load)				
Environ- ment	Ambient temperature	-10 to 50°C, storage:-25 to 65°C				
	Ambient humidity	35 to 85%RH, storage: 35 to 85%RH				
Unit weight		Approx. 196g	Approx. 496g	Approx. 399g	Approx. 468g	

 $\ensuremath{\mathsf{XF.S.}}$  is same with sensor measuring temperature range.

(A)
Photo electric sensor

(B)
Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

> F) Rotary

(G) Connector/

(H) Temp. controller

(I) SSR/ Power controller

(J) Counter

\_\_\_\_

(M) Tacho/ Speed/ Pulse

(N) Display unit

Sensor controller

(P) Switching mode power supply

(Q) Stepper motor& Driver&Controller

(R) Graphic/ Logic panel

S) ield etwork

「) oftware

I) Software

Other

Autonics H-89

Ex) In case of measurement temperature range is from -99.9 to 199.9°C, Full scale is 299.8.

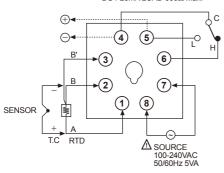
XEnvironment resistance is rated at no freezing or condensation.

## Connections

\*\*RTD: DPt100Ω (3-wire type) \*\*Thermocouple: K, J, R

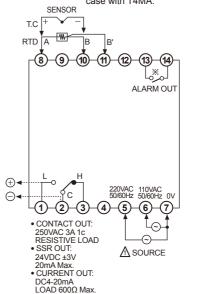
#### T3S

- CONTACT OUT:
   250VAC 2A 1c RESISTIVE LOAD
- SSR OUT : 12VDC ±3V 20mA Max.
- CURRENT OUT : DC4-20mA LOAD 600Ω Max.

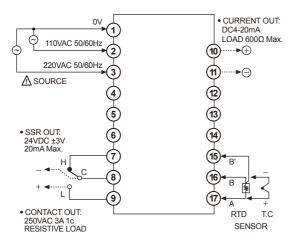


#### T4M

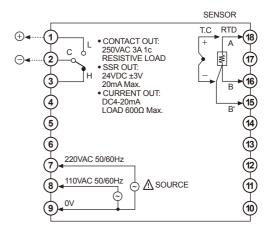
※Although T4M has an alarm terminal, it does not work since it uses the same case with T4MA.



#### T3H

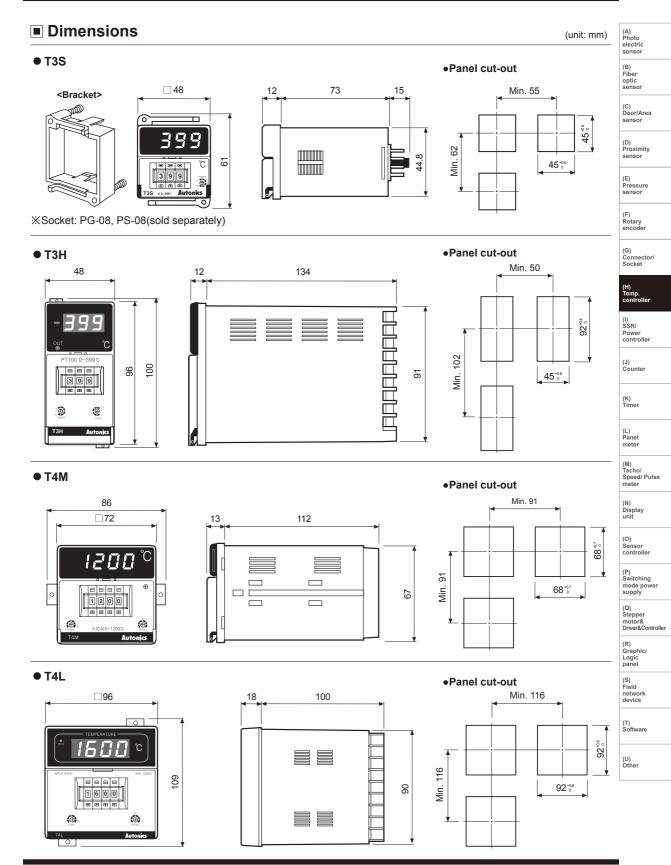


#### • T4L



H-90 Autonics

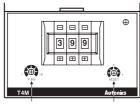
# Standard type



# T3S/ T3H/ T4M/ T4L

# Proper usage

# O Using front adjuster



P.B adjuster Reset adjuste

## P.B adjuster

In case of ON/OFF control, set variable F.S. 0.2 to 3% of hysteresis and in case of P control, set variable F.S. 1 to 10% of hysteresis. However, hysteresis(F.S.  $0.5\% \pm 0.2\%$ ) and proportional band(F.S.  $\pm 3\%$ ) are fixed in T3S.

### Reset adjuster

It corrects offset can be occurred by P control and has F.S. ±3% of adjustable range. Do not operate the adjuster when it is used as ON/OFF control.



- ① Turn left when offset value is higher than setting value. (Direction ①)
- ② Turn right when offset value is lower than setting value. (Direction ②)

# O Normal/Reverse operation

Reverse operation executes to output ON when process value is lower than setting value and it is used for heating. Normal operation runs conversely and is executed for cooling. (This item runs as a reverse operation)

#### O How to select control mode

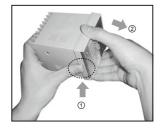
Factory specification is P control. When using ON/OFF control, transfer the switch of control method from P to F after detaching the case from its body. When control output is current output, P control is fixed, there is no switch Pin of control method.





## © Case detachment

#### T4/T3H



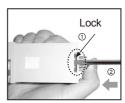
Pressing the front guide of Lock toward ① and squeeze and pull toward ②, it is detached.

#### T4M



Open the front guide, turn it toward ① and pull toward ②, it is detached.

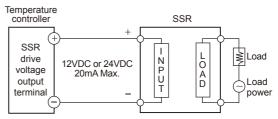
#### T3S



Pressing pin plug ①, raise it up with a driver as ② and it is detached.

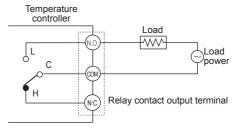
# Application of temperature controller and load connection

## SSR drive voltage output connection



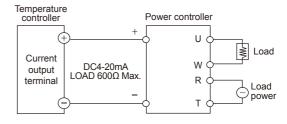
- When using voltage(for driving SSR) in the other purposes, do not over the range of the rated current.
- ※Please aware that each Series has different voltage(for driving SSR).

#### Relay output connection



\*\*Be aware that each model has different contact capacity of relay. When load capacity is high, please use sub relay, which has high contact capacity.

#### Current output connection



- XThe current value of DC4-20mA is available at lower than 600Ω of resistive load.
- ※Refer to the H-141 page for caution for using and simple error diagnosis.